

BSE Topography

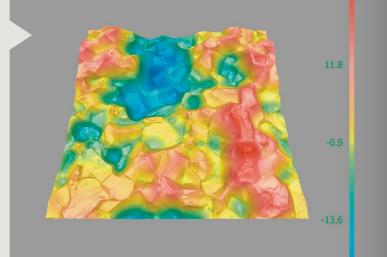
Live and calibrated height measurements, with SEM or FIB-SEM



Add the third dimension to your SEM

Measure surface height with SEM

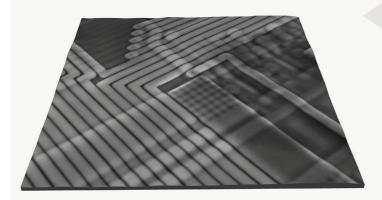
- Use conventional segmented BSE signals
- Measure live with automated topographic reconstruction
- Save topographic data in standard file formats



Visualise complex surfaces in 3D

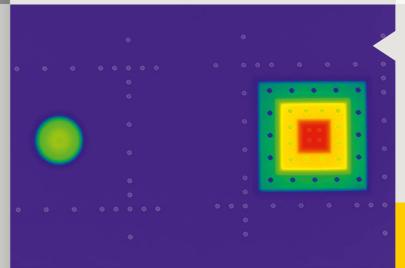
- Add texture from SE, EDS or EBSD maps
- Apply automatic colour gradients as texture
- Export 3D screenshots for high-impact visualisation





Distinguish topography from composition

- Resolve ambiguities in image interpretation
- Reach a wider audience with 3D models, visualisation and printing
- Measure 3D distances and volumes



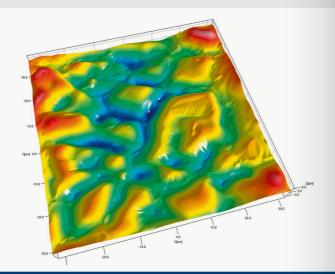
Calibrate and measure heights

- Calibrate measurements with dedicated 3D samples
- Measure 3D positions, distances and angles
- Measure and report height profiles

BSE Topography

Monitor in-situ surface dynamics

- Record surface evolution during in-situ experiments
- Measure deviations from nominal surface
- Quantify 3D changes for different processes



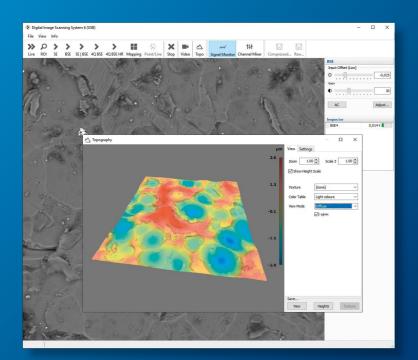
Continue live topography with off-line analysis

- Import data into full feature analysis software
- Measure surface roughness and analyse texture
- Analyse morphology, grain and particle distribution



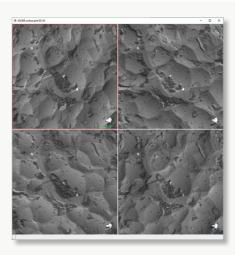


Live calibrated height measurements with any SEM or FIB-SEM



DISS6 - detector control and image acquisition app

- Live surface height reconstruction from BSE signals
- Built-in 3D surface visualization tool
- Configurable workflows with integrated SE and BSE scan profiles

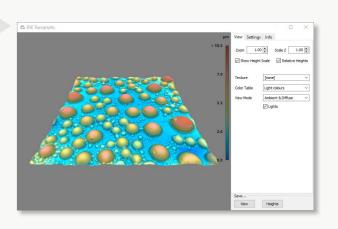


Live topographic reconstruction

- Pan, rotate, tilt, zoom and scale height
- Enhance views with shadows and pseudo-colour
- Texture with BSE average or surface gradients

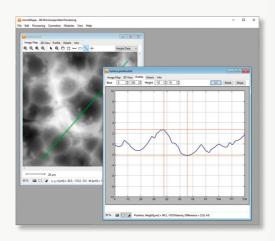
Quantitative 4Q BSE acqusition Factory calibrated amplification and digitization Automatic offset and gain corrections Live inspection of calibrated pixel values

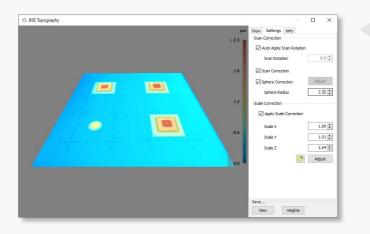
BSE Topography



microShape - surface topography app

- Load, view and edit height and texture layers
- View and manipulate data in 3D
- Extract and export 3D line profiles
- Export standard PLY files for 3D printing



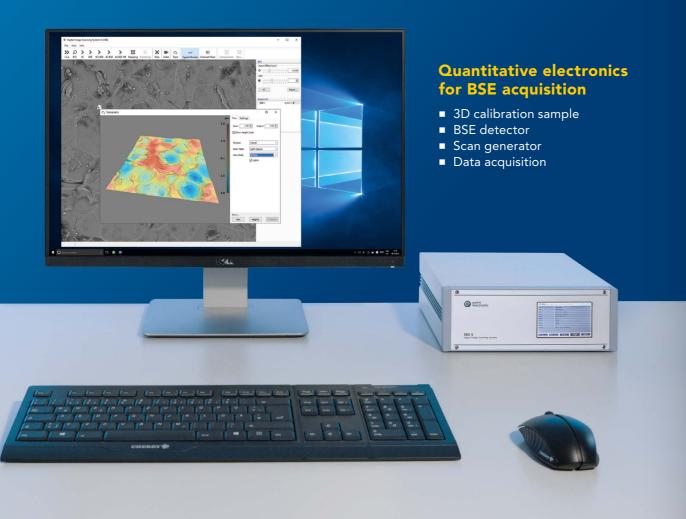


Automated 3D calibration

- Use 3D reference sample to calibrate acquisition
- \blacksquare Get automatic scale parameters for x, y and z
- Save scale parameters for different SEM configurations

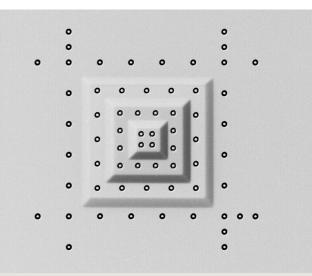


Turn-key solution for any SEM or FIB-SEM



3D calibration sample

- FIB-SEM deposited 3D structures with reference marks for automated calibration
- Calibrated 3D reference data acquired with a metrological SPM system
- Automated, statistical 3D calibration algorithm





BSE detector

- Segmented 4Q Si sensors for topography
- In situ preamplifiers for minimum noise and maximum speed
- Automated insertion/retraction on port mount

BSE Topography

BSE DISS6 imaging

- Signal amplifier, scan generator and image acquisition
- Simultaneous acquisition of all signals
- Advanced offset and gain normalization
- Very large image resolution





3D calibration standard

3× multi-level pyramidal elements
1× spherical element
Reference marks
Produced by FIB deposition
$3\times$ with nominal size of $20\times20\times3~\mu m$
Produced by FIB deposition
10 × 10 × 1 μm (nominal)
Produced by FIB milling
800 nm diameter (nominal)
80 × 80 μm
40 × 40 μm (single pyramid)
Binary file on USB-drive
3D coordinates of reference marks
Calibration report

BSE detector

Sensor	Detector-grade Si chip
	Four-quadrant (4Q) geometry
	Chip on ceramic board mount
	6 mm inner diameter
	20 mm outer diameter
	1 kV minimum acceleration voltage
Pre-amplifier	In-situ mount
	10 ⁵ V/A gain
	200 ns minimum dwell time (gain dependent)
Mechanics	Port mounted, motorized insertion/retraction
	Adjustable height and lateral alignment
	Automatic touch alarm
	Integrated electrical feedtroug

BSE DISS6 imaging

Signal inputs	BSE 14
	AUX 14
BSE 14 amplification	-11 V input offset (calibrated brightness 14)
	11,800× gain (calibrated contrast 14)
	-0.5 0.5 V output offsets (calibrated reference 14)
	BSE average (hardware mix of 14)
	3.4 MHz 34 Hz low-pass filter
4Q BSE control	Automated 4Q global brightness
	Automated 4Q global contrast
	Automated input offsets (dark correction)
	Automated gain normalization (bright correction)
	Automated time filter (matching pixel dwell time)
Digitization	12-bit (calibrated BSE14)
	8× simultaneous signals (BSE14 and AUX14)
	32,000× max. oversampling (pixel averaging)
Scan generator	X and Y scan outputs (calibrated)
	Beam blank output (optional)
	$64k \times 64k$ pixels maximum resolution
	0.5 GPixels maximum frame size (software limit)
	200 ns minimum pixel dwell time (detector limited)
	6 milliseconds maximum pixel dwell time
	256× max. frame average
	50x max. line average
	Frame, line, pixel synchronization (optional)

PC/Laptop, display (optional)

Intel Core i3 minimum
2× USB 2.0 minimum
Windows 117
Network is recommended for remote support
1,280 × 1,024 resolution minimum



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DISS6 app

2.000 app		
	Detector control	Automatic insertion/retraction
		Contrast and brightness
		Input offset and gain normalisation corrections
		Live calibrated pixel values
		Live grayscale 'topographic' and 'compositional' mix
	Topography tool	Live topographic calculation from BSE14
		Live 3D view of height and texture
		Rotation, shift, zoom and scale controls
		Colour look-up-tables
		Automatic spherical correction
		Automatic X, Y and Z scale corrections
	File formats	Compressed 8-bit multi-page TIF with XMP tags
		Raw 16-bit multi-page TIF with XMP tags
		Binary AL3D
		Plain text SDF
	Operating system	Windows 117

microShape app

Topography viewer	AL3D file format
	ASCII, 8/16-bit TIFF file formats
	BCR, Surfer DAT export formats
	2D view of texture and height layers
	3D view of complete topographic data
Topography processing	Crop, rotate, resize
	Scale and shear 3D corrections
	Geometric scan corrections
	Texture layer replacement
4Q BSE reconstruction tool	Common SEM image file formats input
	Configurable detector geometry
	Shape-from-shading algorithm
3D measurements tools	3D points, distances and angles
	Spherical and polynomial surface fit
	3D height line profile graphs
	PDF report file format
	ASCII, CSV data export file formats
3D print	PLY export file format
Operating system	Windows 117
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Parts and cables

3D calibration sample	Standard 1×
BSE detector	Standard 1×
BSE DISS6 imaging	Standard 1×
SEM scan cable	Standard 1×
BSE detector cable	Standard 1×
Mains power cable	Standard 2×
USB cable	Standard 2×
USB flash drive	Standard 1×
PC, keyboard, mouse	Standard 1×
Displays	Standard 1×

Software packages

Drivers	PE USB driver
Libraries	DISS6Control
	DISS6Topography
Software	DISS6 app
	microShape app
	EM Gateway server
	microCal (optional)

Weight and dimensions

Shipping	Typ. 36 × 32 × 150 cm
	Typ. 12.5 kg

Site requirements

Power	2x mains 110/220 VAC single phase 50/60 Hz
	On the same earth as the microscope
Mount	1× flange for BSE detector
Imaging	1× external scan interface on the SEM electronics
Space	BSE DISS6 unit may be placed on the SEM table





Our design principles

We look back on over 30 years of experience in development and manufacture of high-performance instruments and technologies for microscopy.

We are driven by an ambition to expand abilities and to improve performance of electron microscopes.

Our aspiration is to make the best quality tools and to join our customers on their journeys of scientific exploration and discovery.

Performance

Microscopy must be a reliable and enjoyable experience

- Design for highest speed and resolution at the lowest noise
- Develop smart independent controllers for live optimization
- Support new users with intuitive and automated controls
- Assist advanced users with access to all parameters

Efficiency

Microscopes must provide an uninterrupted focus

- Use standard microscope controls and data formats
- Give instant feedback with live image mixing and processing
- Add bespoke software tools and algorithms for repetitive tasks
- Support developers with open access libraries and documentation

Environment

Products and technologies must be sustainable

- Reduce power consumption through smart design
- Minimize material use, embrace reuse where possible
- Save weight and volume for shipping and maintenance
- Enable everyone to develop sustainable innovations

Quantification

Data and control must be in physical units

- Provide calibrated inputs and outputs for quantitative measurements
- Supply samples, procedures, and software for calibration
- Distribute all control parameters in device independent values
- Empower the user to operate the SEM as a measuring device

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